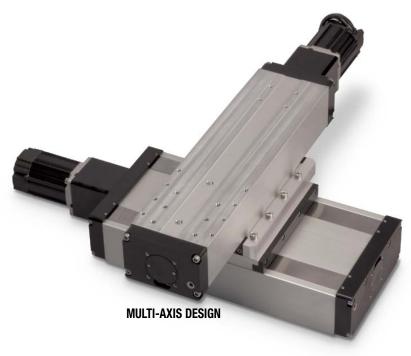
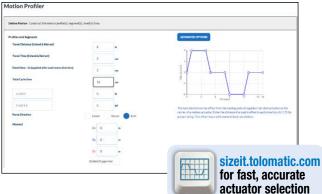


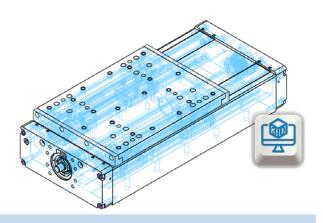
TRS: A Rugged, Accurate Stage

The TRS is a highly capable stage product and is the perfect for a base in multi-axis systems. The machined, rigid design handles high moment loading while providing reliable positioning along the length of travel.

Maximum flexibility is achieved through stroke configurable design, ensuring the right stroke length can be selected to minimize footprint. Online CAD and Sizing tools enable rapid design iterations throughout the design process.





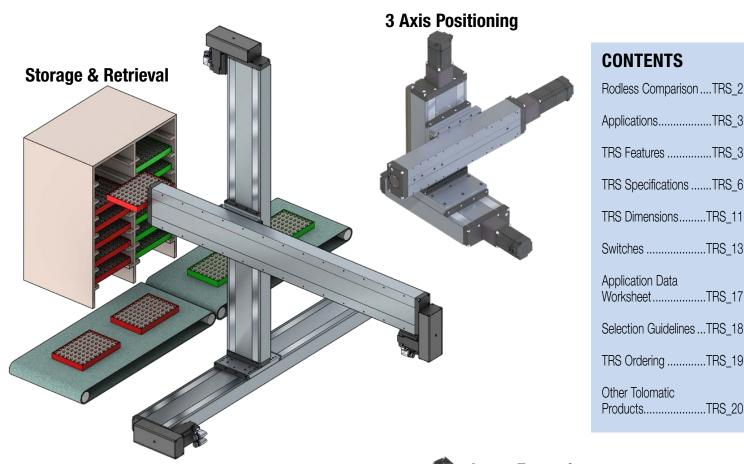


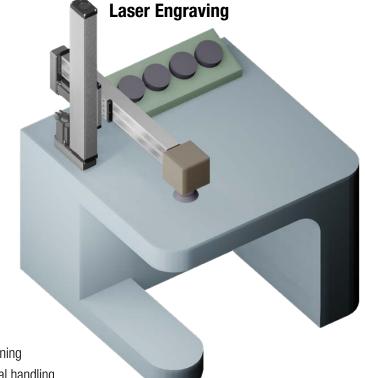
A Comparison of Screw Drive Actuators

-	TRS	B3S	MXE-S	MXE-P					
		ner.	000						
Features:	Superior rigidity, high moment load capacities	Internal bearing, highest load and bending moments	Basic guidance and support	High load and bending moment capacities					
Load up to: (with options)	1,356 lb [615 kg]	8,000 lb [3,629 kg]	1,040 lb [472 kg]	2,584 lb [1,172 kg]					
Thrust up to:	562 lbf [2.5 kN]	2,700 lbf [12 kN]	4,300 lbf [19.1 kN]	4,300 lbf 19.1 kN]					
Speed up to:	36 in/sec [910 mm/sec]	60 in/sec [1,500 mm/sec]	60 in/sec [1,500 mm/sec]	60 in/sec [1,500 mm/sec]					
Stroke Length up to:	43 in [1,090 mm]	179 in [4,550 mm]	179 in [4,550 mm]	179 in [4,550 mm]					
Screw/Nut Type	Ball & Roller	Solid & Ball	Solid & Ball	Solid & Ball					
	www.tolomatic.com for complete information, search by literature number:								
Literature Number:	3600-4222	3600-4176	8300-4000	8300-4000					

(Not all models deliver ALL maximum values listed, i.e.: Maximum thrust may not be available with maximum speed)







Inspection and measurement

Robot Arm Positioning

- Medical equipment
- Pick and place
- Precision grinders
- Stage motion control
- Table positioning
- Test stands
- Machine centers
- Machine tools
- Drilling
- Cutting

- Positioning
- Material handling systems
- Pick and place
- X Y Z axis (2 and 3 axis configurations)

TWIN RAIL STAGE ENCLOSED DESIGN PROFILED RAIL ACTUATOR

ENDURANCE TECHNOLOGY
A Tolomatic Design Principle

REDUCE UNPLANNED DOWNTIME: Endurance Technology features are designed for maximum durability to provide extended service life.

The TRS Twin profile rail stage with enclosed design is built from the ground up to be highly rigid and accurate. Available in 100 and 165 sizes and capable of handling loads up to 1,356 lb (615 kg). To maximize design flexibility, the TRS actuator is stroke configurable to minimize overall machine footprint.

HIGH RIGIDITY

Twin rails each with 2 bearings minimizes deflection for reliable and accurate positioning along the length of travel

CARRIER **TO CARRIER** MOUNTING

- Build a multi-axis system with reduced components by leveraging this standard mounting option
- Tolomatic representatives are available to assist with the sizing

MULTIPLE SCREW TECHNOLOGIES

ROLLER NUT

Roller nuts provide the highest thrust and life ratings available



SCREW ACCURACY

 ± 0.0102 mm/300mm; ± 0.0004 "/ft.

BALL NUT

Ball nuts offer efficiency at a cost effective price

SCREW ACCURACY

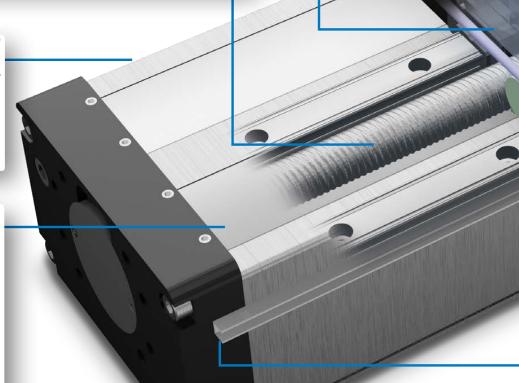
 ± 0.051 mm/300mm; ± 0.002 "/ft.

BREATHER/PURGE PORTS

Positive pressure with air lines and filters helps reduce contamination of the interior of the actuator

IP44 RATED WITH STAINLESS STEEL DUST BANDS

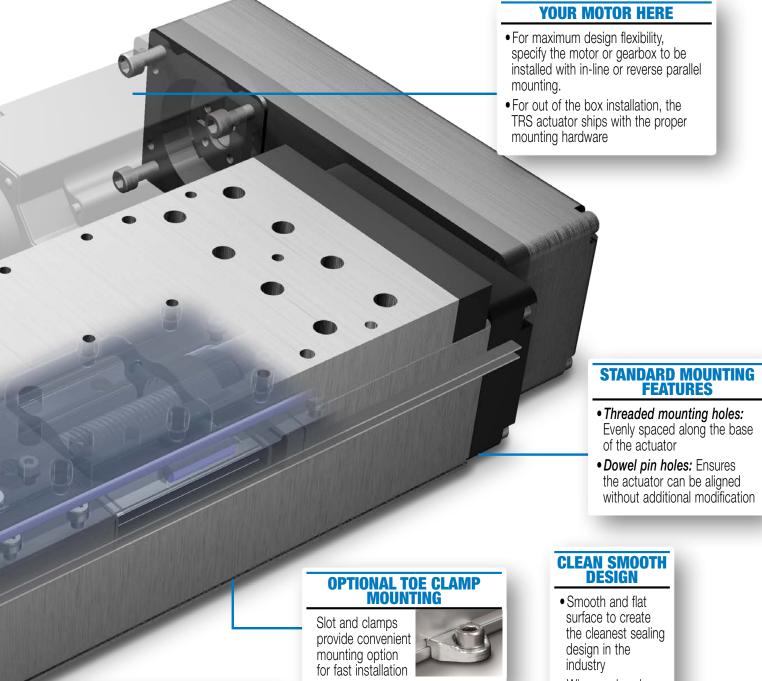
- Perfect for industrial environments
- Limits the amount of contaminants that enter the actuator, which protects components for reduced maintenance and increased uptime







Tolomatic ... MAXIMUM DURABILITY



OPTIONAL SWITCH WITH RAIL

• 12 switch choices in normally open or closed; with flying leads or quickdisconnect

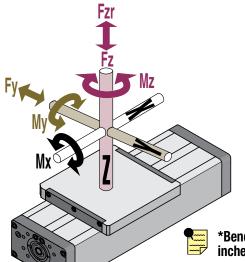


• Easily adjust the location of switches along the length of the actuator

• Wiper and seal are integrated in carrier design to enable clean and smooth operation



BENDING MOMENTS



	MAX. BENDING MOMENTS AND LOADS*								
		Metric	;	U.	U.S. Conventional				
Max. Bending Moments		100	165		100	165			
Mx (Roll)	N-m	101	294	lb-in	895	2,604			
My (Pitch)	N-m	194	284	lb-in	1,718	2,512			
Mz (Yaw)	N-m	175	256	lb-in	1,551	2,269			
Max. Loads									
Fz (Radial)	kg	492	615	lb	1,085	1,356			
Fzr (Reverse Radial)	kg	421	526	lb	928	1,160			
Fy (Lateral)	kg	380	475	lb	838	1,048			
·									

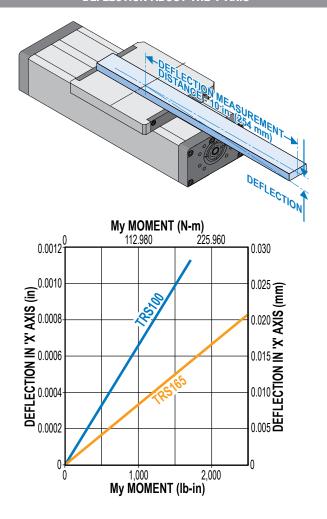
*Bending moments & load specifications are based on (5,000 kM) 200,000,000 linear inches of carrier travel.

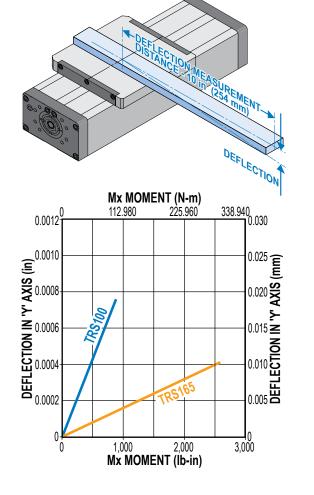
Deflection Considerations: In applications where substantial Mx or My moments come into play, deflection of the actuator frame, carrier and supports must be considered. The deflection values shown in the Load Deflection charts, are based on actuator mounted with its base fully restrained to a surface.

LOAD DEFLECTION

DEFLECTION ABOUT THE Y-AXIS

DEFLECTION ABOUT THE X-AXIS







TRS SPECIFICATIONS

SPECIFICATIONS RELATED TO ACTUATOR SIZE AND SCREW SELECTION

					TRS	LEAD SCF	EWS MET	RIC			
						MDL	₩		INERTIA		으로
OR		9		유승능		MAXIMUM THRUST	MAXIMUM Stroke	BASE AC	TUATOR	PER/in	DYNAMIC FRICTION TORQUE
ACTUATOR	SCREW	LEAD	TOR NFIG	LEAD ACCU- RACY	BACKLASH			In Line	Rev. Parallel	OF STROKE	
AC.	IOS IOS	(mm)	MOS	(mm/300)	(mm)	(N)	(mm)	(kg-m ² x 10 ⁻⁶)	(kg-m ² x 10 ⁻⁶)	(kg-m ² x 10 ⁻⁶)	(N-m)
TRS100	BNM05	5	ВОТН	0.100	0.07 - 0.12	2,500	750	40.82	135.32	1.29	0.18
1113100	BNM10	10	ВОТН	0.100	0.07 - 0.12	2,500	750	45.35	139.85	1.29	0.19
	BNM05	5	ВОТН	0.100	0.07 - 0.12	2,500	1,100	40.67	135.17	1.29	0.18
	BNM10	10	ВОТН	0.100	0.07 - 0.12	2,500	1,100	43.30	137.80	1.29	0.19
TRS165	RN05	5	LMI	0.010	0.03	2,500	575	38.48	_	0.99	0.21
100100	RN05	5	RP	0.010	0.03	2,500	557	_	132.98	0.99	0.23
	RN10	10	LMI	0.010	0.03	2,500	575	41.67	_	0.99	0.21
	RN10	10	RP	0.010	0.03	2,500	557	_	136.16	0.99	0.23

	TRS LEAD SCREWS u.s. conventional												
						M	MAXIMUM Stroke		INERTIA		VIIC JE JE		
TOR	REW DE	9	48	LEAD ACCU- RACY		MAXIMUM Thrust		BASE ACTUATOR		PER/in	₹55		
ACTUATOR		LEAD	MOTOR	AC RA	BACKLASH	Z I		In Line	Rev. Parallel				
AC	SCRE	(mm)	MO	(in/ft)	(in)	(lbf)	(in)	(lb-in ²)	(lb-in ²)	(lb-in ²)	(lb-in)		
TRS100	BNM05	5	вотн	0.004	0.0028 - 0.0050	562	29.5	0.1397	0.4631	0.0044	1.56		
INSTUU	BNM10	10	вотн	0.004	0.0028 - 0.0050	562	29.5	0.1552	0.4786	0.0044	1.69		
	BNM05	5	вотн	0.004	0.0028 - 0.0050	562	43.3	0.1392	0.4626	0.0044	1.56		
	BNM10	10	вотн	0.004	0.0028 - 0.0050	562	43.3	0.1482	0.4716	0.0044	1.69		
TRS165	RN05	5	LMI	0.0004	0.0012	562	22.6	0.1317	_	0.0034	1.88		
Inoros	RN05	5	RP	0.0004	0.0012	562	21.9	_	0.4551	0.0034	2.00		
	RN10	10	LMI	0.0004	0.0012	562	22.6	0.1426	_	0.0034	1.88		
	RN10	10	RP	0.0004	0.0012	562	21.9	_	0.466	0.0034	2.00		

SCREW TYPE DESCRIPTION RN Roller Nut BN Ball Nut



Contact the factory for higher accuracy and lower backlash options.

TRS CARRIER TO CARRIER MAX. LOAD





ACTUATOR SPECIFICATIONS

		TRS	100		TRS165				
		Ball Nut		Ball	Nut	Roller Nut			
		LMI	RP	LMI	RP	LMI	RP		
Carrier Assembly Weight	kg	2.16	2.16	3.20	3.20	3.55	3.55		
Base Weight (incl. carrier)	kg	5.97	7.79	8.44	10.26	8.74	10.56		
Weight per unit of stroke	kg/mm	0.010	0.010	0.015	0.015	0.014	0.014		
Carrier Assembly Weight	lb	4.75	4.75	7.06	7.06	7.82	7.82		
Base Weight (incl. carrier)	lb	13.17	17.18	18.61	22.62	19.28	23.29		
Weight per unit of stroke	lb/in	0.56	0.56	0.81	0.81	0.80	0.80		
Temperature Range			4-5	4 °C; 40-13	30 °F				

FRICTION FORCE

 $N = 0.003 \times LOAD (kg) + 17.6$ $lbf = 0.0003 \times LOAD (lb) + 3.96$

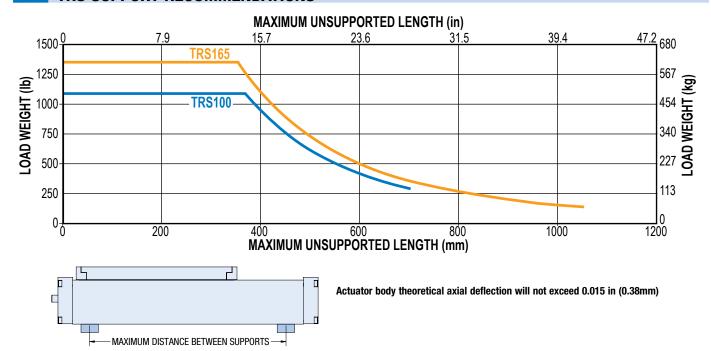
STRAIGHTNESS AND FLATNESS

Length of	mm	60	120	180	240	300	360	420	480	540	600	660	720	780	840	900	960	1,020	1,080	1,100
Travel	in	2.4	4.7	7.1	9.5	11.8	14.2	16.5	18.9	21.3	23.6	26.0	28.4	30.7	33.1	35.4	37.8	40.2	42.5	43.3
Straightness/ Flatness	μm	20	21	22	23	24	26	27	28	29	30	32	33	34	35	36	38	39	40	40



- Listed values are intended for reference purposes only, and not as an engineering standard of absolute tolerance for a given actuator. Reference values are measured in ideal conditions. Actual values in the field may vary due to temperature, mounting surface, or other environmental factors.
- Heat generated by the motor and drive should be taken into consideration as well as linear velocity and work cycle time. For applications that
 require operation outside of the recommended temperature range, contact the factory.
- An option is available at additional cost to document the straightness and flatness values specific to the actuator, contact the factory prior to ordering.

TRS SUPPORT RECOMMENDATIONS

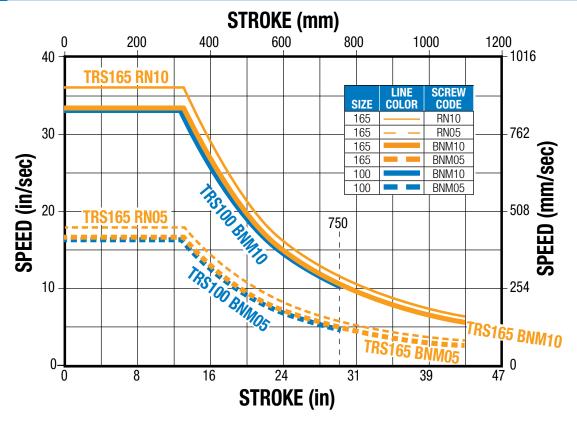




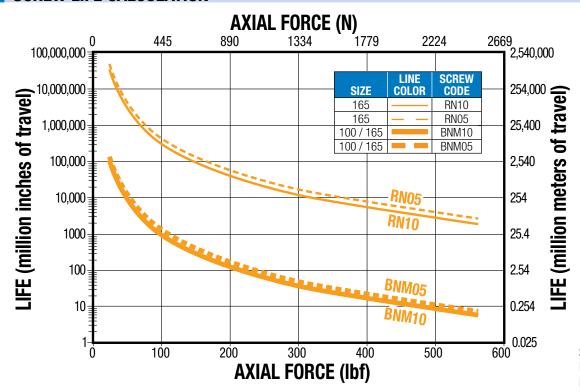


SCREW/NUT COMBINATIONS

TRS BALL & ROLLER SCREW CRITICAL SPEED CAPACITIES



SCREW LIFE CALCULATION



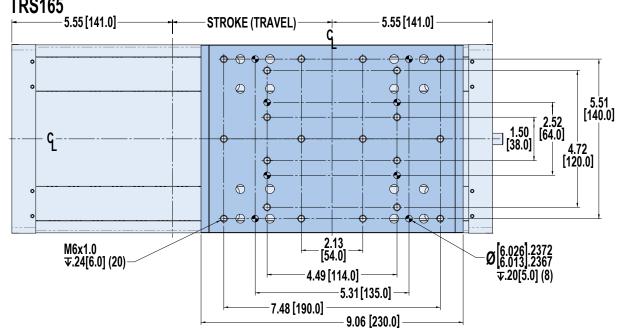
SCREW TYPE DESCRIPTION RN Roller Nut BN Ball Nut

^{**}Life indicates theoretical maximum life of screw only, under ideal conditions and does not indicate expected life of actuator.

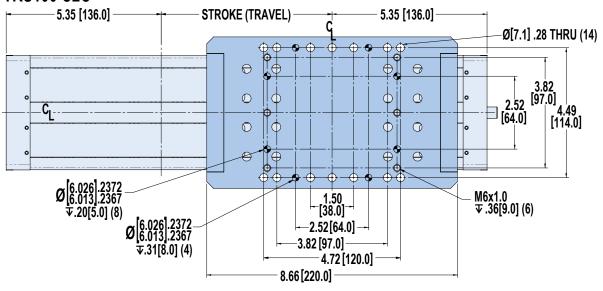


DIMENSIONS, Top View TR\$165

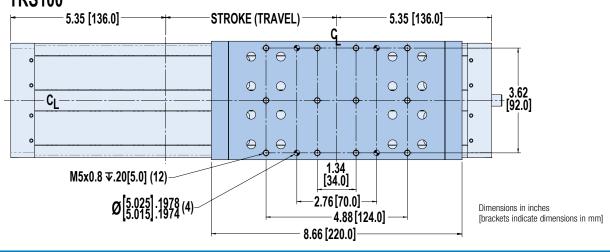




TRS100 C2C

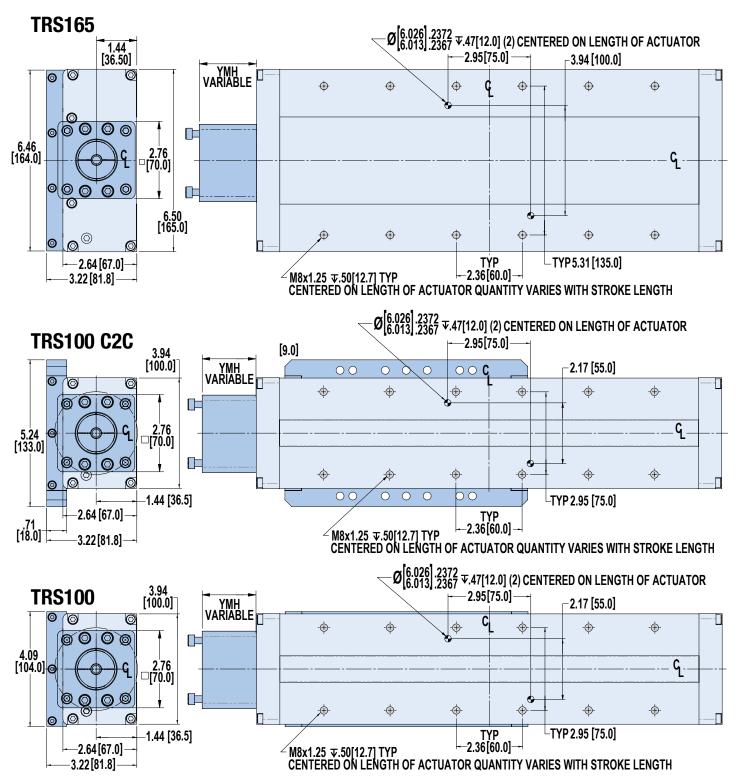


TRS100



DIMENSIONS, End & Bottom Views

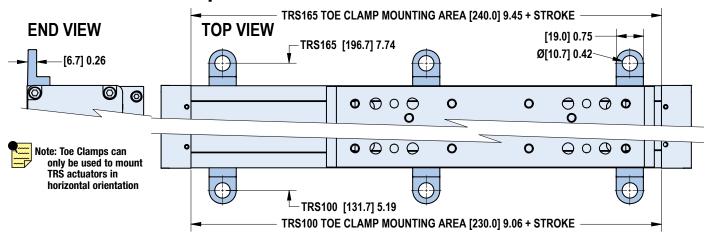




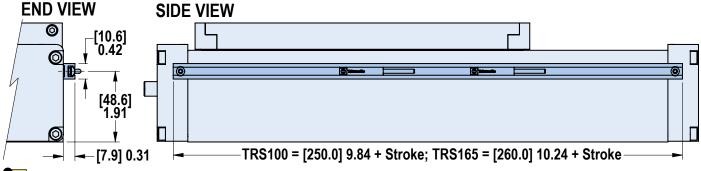
Dimensions in inches [brackets indicate dimensions in mm]

DIMENSIONS: Toe Clamps



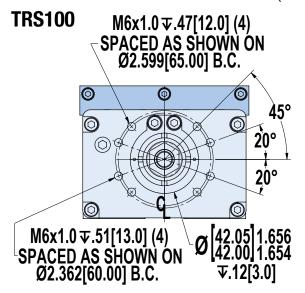


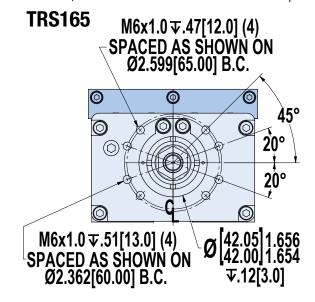
DIMENSIONS: Switch Rail



Note: Switch rail is installed on the right side of the actuator (from the motor end) for all motor mounting configurations except RPR1 where it is installed on the left side of the actuator.

DIMENSIONS: No Motor Mount (threaded holes and bolt circle; when no motor mount is selected)

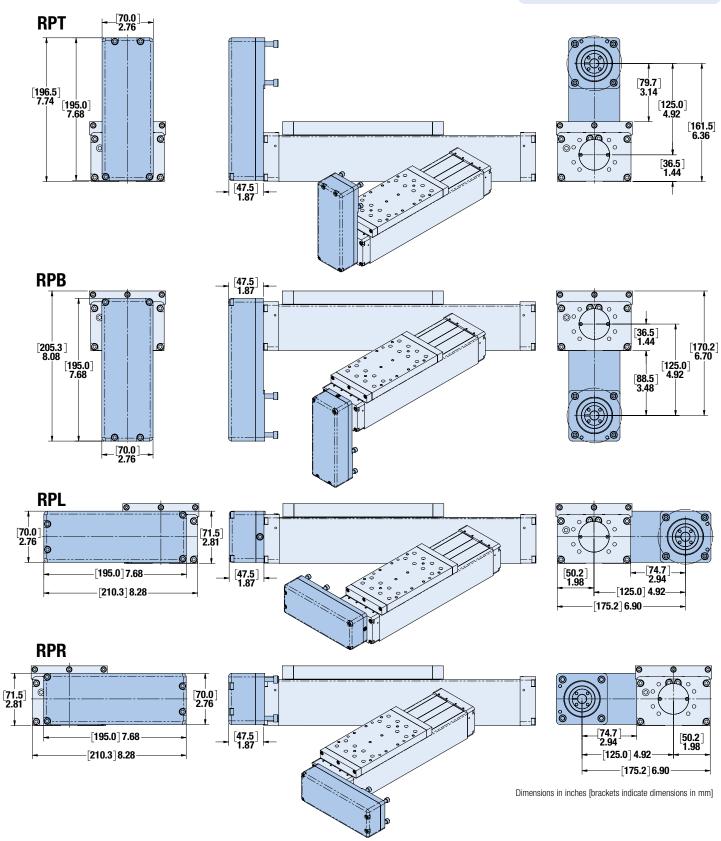




Dimensions in inches [brackets indicate dimensions in mm]

DIMENSIONS: RP Motor Mounts: TRS100



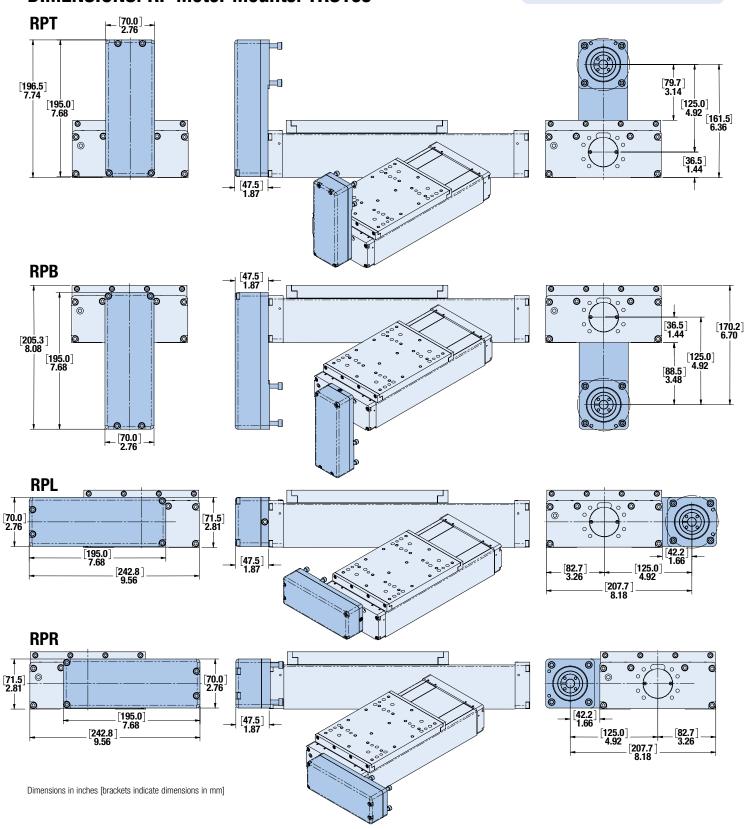


A

*LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

DIMENSIONS: RP Motor Mounts: TRS165





A

*LARGE FRAME MOTORS AND SMALLER SIZE ACTUATORS: Cantilevered motors need to be supported, if subjected to continuous rapid reversing duty and/or under dynamic conditions.

SWITCHES

SPECIFICATIONS





TRS products offer a wide range of sensing choices. There are 12 switch choices: reed, solid state PNP (sourcing) or solid state NPN (sinking); in normally open or normally closed; with flying leads or quick-disconnect.

Commonly used for end-of-stroke positioning, these switches allow drop-in installation anywhere along the rail on the side of the actuator. The one-piece design includes the retained fastening hardware.

Switches are used to send digital signals to PLC (programmable logic controller), TTL, CMOS circuit or other controller device. Switches contain reverse polarity protection. Solid state QD cables are shielded; shield should be terminated at flying lead end.

All switches are CE rated and are RoHS compliant. Switches feature bright red or yellow LED signal indicators; solid state switches also have green LED power indicators.

	Order Code	Lead	Switching Logic	Power LED	Signal LED	Operat- ing Voltage	**Power Rating (Watts)	Switching Current (mA max.)	Current Consump- tion	Voltage Drop	Leakage Current	Temp. Range	Shock / Vibration
	RY	5m	SPST Normally	_	Red	5 - 240							
REED	RK	QD*	Open	Tolomatio	C 81009082	AC/DC **10.0	100mA		3.0 V	_			
IILLD	NY	5m	SPST Normally	_	Yellow	5 - 110	5 - 110 AC/DC			max.			
	NK	QD*	Closed	Tolomatio	81009084	AC/DC							
	TY	5m	PNP (Sourcing)	Green	Yellow							14	
	TK	QD*	Normally Open	Tolomatio	81009088					2.0 V max.	0.05 mA max.	to 158°F [-10 to 70°C]	50 G / 9 G
	KY	5m	NPN (Sinking)	Green	Red								
SOLID	KK	QD*	Normally Open	Tolomatio	81009090	10 - 30	**3.0	100mA	20 mA @				
STATE	PY	5m	PNP (Sourcing)	Green	Yellow	VDC	0.0	10011111	24V				
	PK	QD*	Normally Closed	Tolomatio	C 81009092								
	ΗY	5m	NPN (Sinking)	Green	Red								
	HK	QD*	Normally Closed	Tolomatio	C 81009094								

^{*}QD = Quick-disconnect

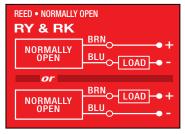
 \mathbf{A}^{**} WARNING: Do not exceed power rating (Watt = Voltage x Amperage). Permanent damage to sensor will occur.

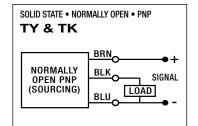


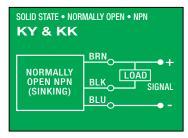
Enclosure classification IEC 529 IP67 (NEMA 6)

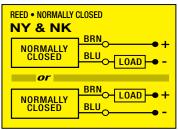
CABLES: Robotic grade, oil resistant polyurethane jacket, PVC insulation

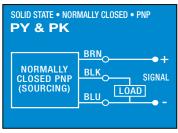
WIRING DIAGRAMS

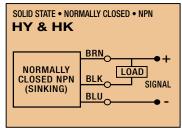


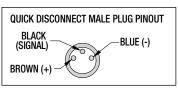


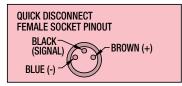




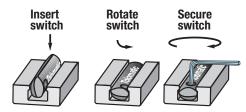








SWITCH INSTALLATION AND REPLACEMENT



☐ Y - direct connect

Place switch in side groove on tube at desired location with "Tolomatic" facing outward. While applying light pressure to the switch, rotate the switch is halfway into the groove. Maintaining light pressure, rotate the switch in the opposite direction until it is fully inside the groove with "Tolomatic" visible. Re-position the switch to the exact location and lock the switch securely into place by tightening the screw on the switch.

SWITCH DIMENSIONS

DETECTION POINT SOLID STATE

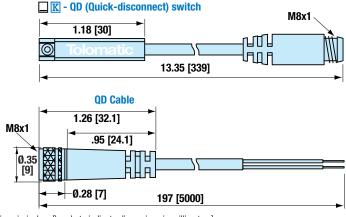
DETECTION POINT REED

.31 [8]

.51 [13]

197 [5000]





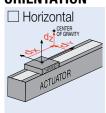
Dimensions in inches [brackets indicate dimensions in millimeters]

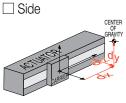
COMPILE APPLICATION REQUIREMENTS

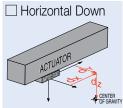
APPLICATION DATA WORKSHEET

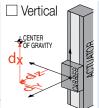
Fill in known data. Not all information is required for all applications

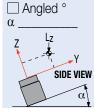
ORIENTATION

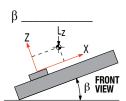












 M_X

□ Load attached to carrier OR □ Load supported by other mechanism

DISTANCE FROM CENTER OF CARRIER **TO LOAD CENTER**





millimeter

STROKE LENGTH

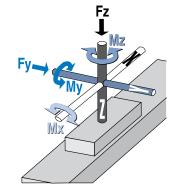
inch (SK) (U.S. Standard)

☐ millimeters M (Metric)

NOTE: If load or force on carrier changes during cycle use the highest numbers for calculations

LOAD	
□lh	

(U.S. Standard) (Metric)



THRUST REQUIRED

SCREW DRIVE

 \square N



PRECISION

Repeatability

☐ inch ☐ millimeters

OPERATING ENVIRONMENT

Temperature, Contamination, etc.

 \square lbf. (U.S. Standard) (Metric)

MOVE PROFILE

Move Distance ☐ inch ☐ millimeters Dwell Time After Move_ Max. Speed _ ☐ in/sec mm/sec

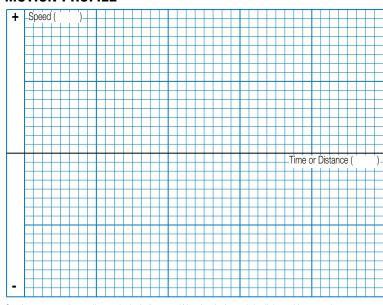
MOVE	TIME	

sec

NO. OF CYCLES

per minute per hour





Graph your most demanding cycle, including accel/decel, velocity and dwell times. You may also want to indicate load variations and I/O changes during the cycle. Label axes with proper scale and units.



We will provide any assistance needed to determine the proper actuator for the job.

FAX 1-763-478-8080

Inline

EMAIL help@tolomatic.com

CONTACT INFORMATION

Name, Phone, Email Co. Name. Etc.

sizeit.tolomatic.com for fast, accurate

actuator selection

SELECTION GUIDELINES

The process of selecting a load bearing actuator for a given application can be complex. It is highly recommended that vou contact Tolomatic or a Tolomatic Distributor for assistance in selecting the best actuator for your application. The following overview of the selection quidelines are for educational purposes only. The Tolomatic Sizelt Software is also available on Tolomatic.com

CHOOSE ACTUATOR SIZE

Choose an actuator that has the thrust, speed and moment load capacity to move the load. Use the Critical Speed graph (page TRS_9) for the screw and the Moment and Load Capacity table (pg. TRS_6) for the actuator.

2 COMPARE LOAD TO MAXIMUM LOAD CAPACITIES

Calculate the application load (combination of load mass and forces applied to the carrier) and application bending moments (sum of all moments Mx, My, and Mz applied to the carrier). Be sure to evaluate the magnitude of dynamic inertia moments. When a rigidly attached load mass is accelerated or decelerated. its inertia induces bending moments on the carrier. Careful attention to how the load is decelerated at

the end of the stroke is required for extended actuator performance and application safety. If either load or any of your moments exceed figures indicated in the Moment and Load Capacity table (pg. TRS_6) for the actuator consider:

- Higher capacity bearing style
- 2) A larger actuator size
- 4) External guide system

3 CALCULATE LOAD

For loads with a center of gravity offset from the carrier account for both applied (static) and dynamic loads. The load factor (LF) must not exceed the value of 1.0

$$L_F = \frac{Mx}{Mx_{max}} + \frac{My}{My_{max}} + \frac{Mz}{Mz_{max}} + \frac{Fy}{Fy_{max}} + \frac{Fz}{Fz_{max}} \le 1.0$$

If LF exceeds the value of 1.0, consider the four choices listed in step #2.

4 ESTABLISH YOUR MOTION PROFILE AND CALCULATE ACCELERATION RATE

Using the application stroke length and maximum carrier velocity (or time to complete the linear motion), establish the motion profile. Select either triangular (accel-decel) or trapezoidal (accel-constant speed-decel) profile. Now calculate the maximum acceleration and deceleration rates of the move. A TRS twin rail screw-driven actuator speed should not exceed the value in the critical speed capacity graph (page TRS_9) for the screw/nut combination chosen. Also. do not exceed safe rates of dvnamic inertia moments determined in step #3.

5 SELECT THE LEAD SCREW

Based on the application requirements for accuracy,

backlash, quiet operation, life, etc. select the appropriate screw type (ball screw or roller screw) and the pitch (lead). For additional information on screw selection, consult "Selecting the Optimal Screw Technology" (#9900-4644) available at www.tolomatic.com.

6 SELECT MOTOR AND DRIVE

To help select a motor and drive, leverage the Tolomatic SizeIt software, available on Tolomatic.com to calculate the application thrust and torque requirements.

7 CONSIDER OPTIONS

- TC Toe clamps
- C2C Carrier-to-carrier mounting
- Switches Reed, Solid State PNP or NPN, all available normally open or normally closed

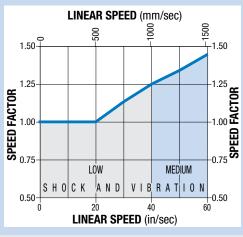


sizeit.tolomatic.com for fast, accurate actuator selection

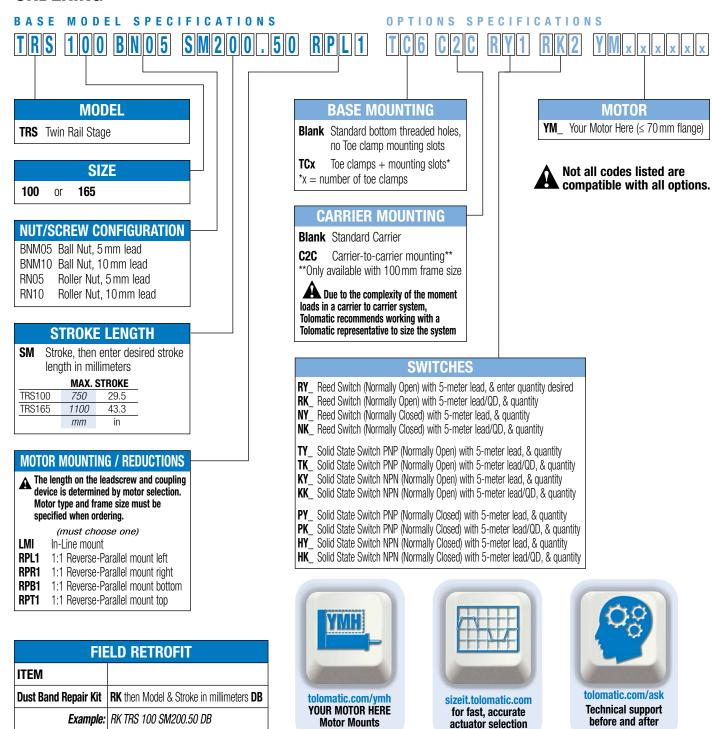
Use Tolomatic Sizing Software to determine available options and accessories based on your application requirements.

SPEED FACTOR

FOR APPLICATIONS WITH HIGH SPEED OR SIGNIFICANT SHOCK AND VIBRATION: Loads and bending moments must be multiplied by speed factor from the graph below to obtain full rated life of profiled rail bearing system.



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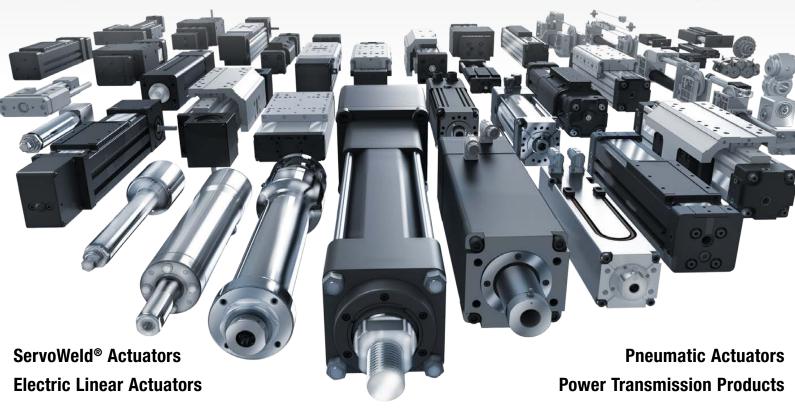
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